

Adaptive Data Services & Solutions for Connected & Autonomous Vehicles



Overview



Connected Car Data Ecosystem





Intelligent Vehicle Services









Driver Monitoring & Alerting





Our Solution

KnowGo Car

A vehicle data management & services platform that allows endusers and service providers to leverage both personally identifiable and other types of sensitive data in a way that is secure, privacy-preserving, ethical, and adaptable across country borders and industry sectors.



- ✓ Industry 1st GDPR-by-design vehicle data management platform, future-proof for future regulation and regulatory variance.
- Industry 1st platform that can deal with cross-border data service continuity, compliance, and auditing.
- ✓ Run in the cloud, in-vehicle, or on-device.
- Bring connected car services to existing non-connected vehicles.
- Integrate into head unit or project to in-vehicle display.





Real-Time Dynamic Adaptation

All Platform Components and Applications provide run-time adaptation capabilities, allowing **applications to be refactored and reconfigured in real-time** in response to changes in:



KnowGo High-Level System Architecture



KnowGo System Architecture



Kubernetes Deployment Scenarios



Edge Gateway Heterogeneity Challenges

- Edge Gateways (and by extension, ECUs and head units) are becoming increasingly powerful due to the continual addition of new types of accelerators. However:
 - Each requires its own unique container runtime.

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- In the case of Tensorflow, each requires adaptation/conversion from base Tensorflow model (TFLite, TensorRT), with accelerator-specific requirements (e.g. quantization-aware training/post-training quantization).
- Available memory limits these primarily to inference-only workloads, with training pushed back to Cloud or HPC resources on the backend.
- Possible to leverage different accelerators at different stages of the image processing pipeline within the same application:
 - FPGA/Vision Processor for preparing images for inference
 - GPU/NVDLA/NCS2/Tensor units for carrying out inference
- Possible to use different accelerators for supplying same model:
 - Both in terms of Edge-focused model zoo, and at run-time via ONNX





Edge Gateway Feature Detection

Node feature discovery and self-labelling provides an overview of available accelerators and hardware characteristics:



MLOps Pipeline



Cloud vs. Edge Containers in CI/CD Pipeline



Image Variants: One Application, Multiple Execution Possibilities





Case Study #1: KnowGo Driver Monitor







- Different accelerators may be under contention at different times, requiring deployed applications to adapt:
 - GPU preferred for driver monitoring, but may become unavailable when a child in the back takes it over to play a game
 - Driver monitoring can be handled by multiple accelerators
 - Gaming can only be handled by the GPU
 - Edge-based GPUs can not presently be partitioned or sliced (no GPU virtualization / NVIDIA GRID)
 - Must hand the application off to another resource while minimizing service disruption.





Case Study #2: KnowGo Score



SAE J3016[™] LEVELS OF DRIVING AUTOMATION



These are driver support features

These are automated driving features

What do these eatures do?	These features are limited to providing warnings and momentary assistance	These fea- tures provide steering OR brake/accelera- tion support to the driver	These features provide steering AND brake/ acceleration support to the driver	These features can drive the ve- hicle under limited conditions and will not operate unless all required conditions are met		This feature can drive the vehicle under all conditions
Example Features	 automatic emer- gency braking blind spot warn- ing lane departure warning 	 Land centering OR Adaptive cruise control 	 Land centering AND Adaptive cruise control at the same time 	• traffic jam chauffeur	 local driverles taxi pedals/steerin wheel may or may not be installed 	s • same as level 4, but feature can drive every- where in all condition







Thank You!